

Simplified Approach for Modeling a PV/Wind Hybrid Renewable Energy system using Simulink/Matalab.

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Abstract

Photovoltaic (PV) array which is composed of modules is considered as the fundamental power conversion unit of a PV generator system. The PV array has nonlinear characteristics and it is quite expensive and takes much time to get the operating curves of PV array under varying operating conditions. In order to overcome these obstacles, common and simple models of solar panel have been developed and integrated to many engineering software including Matlab/Simulink. However, these models are not adequate for application involving hybrid energy system since they need a flexible tuning of some parameters in the system and not easily understandable for readers to use by themselves. Therefore, this paper presents a step-by-step procedure for the simulation of PV cells/modules/arrays with Tag tools in Matlab/Simulink. A 200-Watt solar panel is used as reference model. The output characteristics curves of the model match the characteristics of the solar panel after simulation. The mathematical modeling of the PV was demonstrated step by step, Wind Turbine performance was simulated and observed, the output voltage of the turbine was 240V matched the calculated value.

A step-by-step procedure for simulating a PV array with Tag tools, using friendly icons and dialogs in Matlab/Simulink block libraries is shown in this work. This modeling procedure serves as an aid to help people understand the I–V and P–V operating curves of PV module. The research is the first step to study a hybrid system where a PV power generation connecting to other renewable energy production sources like wind or biomass energy systems is applied and simplified.

KEY WORDS: Photovoltaic array, Matlab/Simulink, Hybrid, Tag

1. INTRODUCTION

Solar (PV) systems capture the sunlight and directly convert it into electricity. Photovoltaic (PV) cell is the basic element of a PV system. A photovoltaic cell is a semiconductor diode whose p-n junction is open to the light. When sunlight strikes the solar cell junction, free electrons and holes are generated and a current is delivered to the load when it is short circuited. A grouping of PV cells forms a solar panel. To obtain large output voltage solar panels are formed by connecting PV cells in series and to achieve large output current cells are connected in parallel. A function in Matlab environment was developed to calculate the current output from the following parameters: Voltage, solar irradiation and temperature in the study of [1].

A method which applies Matlab m-file and C-language programming is even more difficult to clarify [2]. Another writer proposed a model based on solar cell and array's mathematical equations and built with common blocks in Simulink environment in [3,4,5 and 6].

Rated output power and rate output wind speed.

As the wind speed rises above the cut-in speed, the level of electrical output power rises rapidly too. The limit to the generator output is called the rated power output and the wind speed at which it is reached is called the rated output wind speed. At higher wind speeds, the design of the turbine is arranged to limit the power to this maximum level and there is no further rise in the output power. How this is done varies from design to design but typically with large turbines, it is done by adjusting the blade angles so as to keep the power at the constant level.

2. MATERIALS AND METHODS**Components description**

The configuration used in Fig. 1 consists of wind energy and PV energy systems, DG, battery bank, charge controller, bidirectional converter, main load, and dummy load. The dispatch of this configuration is easy to be understood. The main load is supplied primarily from the WT and PV array through the bidirectional converter.

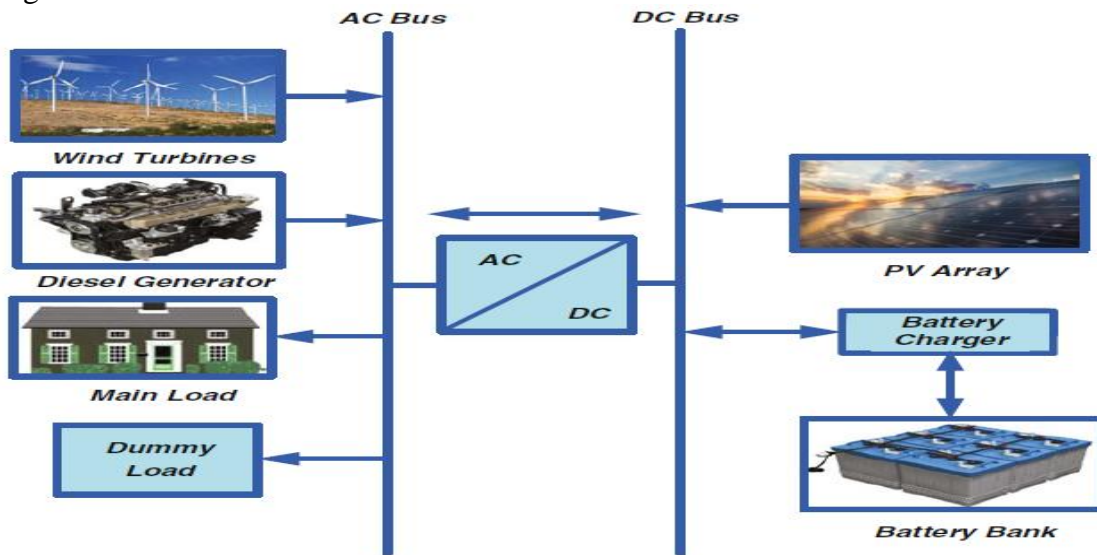


Fig. 2 Schematic diagram of the hybrid PV/wind/diesel/battery energy system courtesy of(Springer International Publishing)

The excess power from the wind energy system and/or PV energy system above the load demand is stored in the battery bank until the batteries are completely charged.

If the battery storage is full; excess power (i.e., dummy power) will be used to supply certain special loads (i.e., dummy loads), such as loads for cooling and heating purposes, water pumping, and charging the batteries of emergency lights. used. Mathematical modeling of the proposed HRES parts is detailed in the following subsections. Among other authors, a proposed model is based on solar cell and array's mathematical equations and built with common blocks in Simulink environment in [7,8,9 and 10]. In these studies, the effect of environmental conditions (solar insolation and temperature), and physical parameters (diode's quality factor, series resistance R_s , shunt was discussed and noted.

A step-by-step procedure for simulating PV module with subsystem blocks with user-friendly icons and dialog in the same approach with Tarak Salmi and Savita Nema was developed by Jena, Pandiarajan and Muthu et al. However, the biggest gap of the studies mentioned above is shortage of

considering the effect of partially shading condition on solar PV panel's operation. In other researches, authors used empirical data and Lookup Table or Curve Fitting Tool (CFtool) to build P–V and I–V characteristics of solar module [11]. The disadvantage of this method is that it is quite challenging or even unable to collect sufficient data for its application. From the work of [12] and [13], a solar cell block which has already been built in Simscape/Simulink environment is employed. With this block, the input parameters such as short circuit current, open circuit voltage, etc. are provided by manufacturers. The negative point of this approach is that some parameters including saturation current, temperature, and so on cannot be evaluated. Solar model developed with Tag tools in Simulink environment is recorded in the research of [14], and [15], etc. In these papers, only two aspects (solar irradiation and temperature) are investigated without providing step-by-step simulation procedure. Hence, lack of presenting step-by-step simulation procedure is a concern for readers and researchers to follow and do simulation by themselves. Therefore, the study proposes an easy model built with Tag tools in Simulink environment. The proposed model shows strength in investigating all parameters' influence on solar PV array's operation. In addition, a unique step-by-step modeling procedure shown allows readers to follow and simulate by themselves to do research.

3.0 METHODS

Modeling the system with equations and Building the Simulink Block Diagram is the first step in realising the first objective.

(a) Modeling of the PV Array, 1 shows the equivalent circuit of a PV cell.

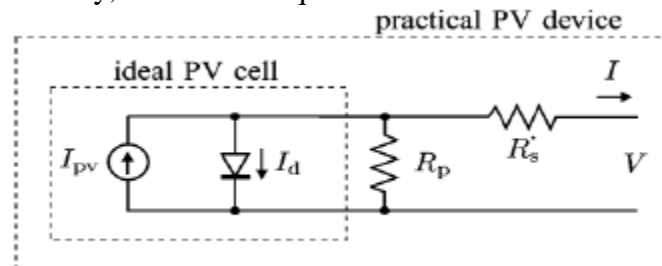


Fig.1: Equivalent circuit of a PV cell

The current source I_{ph} is the PV cell photocurrent. R_{sh} and R_s are the shunt and series resistances of the cell, (internal resistance). The value of R_{sh} is always of large magnitude and that of R_s is usually very small, hence they may be neglected to simplify the analysis [16]. Practically, PV cells are arranged in larger segments called PV modules and these segments are connected in series or parallel to represent PV arrays which are used to produce electricity in Photovoltaic systems. The equivalent circuit for PV array is shown in Fig.1 The voltage–current characteristic equation of a solar cell is provided as [17].

$$\text{Module photo-current, } I_{ph} = [I_{sc} + K_i(T - 298)] \times I_r / 1000 \quad (1)$$

Here, I_{ph} : photo-current (A); I_{sc} : short circuit current (A); K_i : short-circuit current of cell at 25 °C and 1000 W/m²; T : operating temperature (K); I_r : solar irradiation (W/m²). Module reverse saturation current I_{rs} is expressed as [18]

$$I_{rs} = I_{sc} / [\exp(qV_{oc}/N_s k n T) - 1] \quad (2)$$

Here, q : electron charge, = 1.6×10^{-19} C; V_{oc} : open circuit voltage (V); N_s : number of cells connected in series; n : the ideality factor of the diode;

k : Boltzmann's constant, = 1.3805×10^{-23} J/K.

Where I_{pv} , cell = incident light current (which is directly proportional to the sun radiation),

I_d = Shockley diode equation

I_{rsat} , cell = reverse saturation or leakage current of the diode

q = electron charge ($1.60217646 \times 10^{-19}$ C)

k = Boltzmann constant ($1.3806503 \times 10^{-23}$ J/K)

T = temperature of the p-n junction

a = diode ideality constant

The module saturation current I_{sat} varies with the cell temperature, which is given by [19] :

$$I_{sat} = I_{rs} \left[\frac{T}{T_r} \right]^3 \exp \left[\frac{q \times E_{g0}}{nk} \left(\frac{1}{T} - \frac{1}{T_r} \right) \right] \quad (3)$$

Here, T_r : nominal temperature = 298.15 K; E_{g0} : band gap energy of the semiconductor, = 1.1 eV; The current output of PV module is:(Nguyen, 2015)

$$I = N_p \times I_{ph} - N_p \times I_0 \times \left[\exp \left(\frac{V/N_s + 1 \times R_s/N_p}{n \times V_t} \right) - 1 \right] - I_{sh} \quad (4)$$

With:

$$V_t = \frac{k \times T}{q} \quad (5)$$

And (Nguyen,2015)

$$I_{sh} = \frac{V \times N_p / N_s + I \times R_s}{R_{sh}} \quad (6)$$

Here: N_p : number of PV modules connected in parallel; R_s : series resistance (Ω); R_{sh} : shunt resistance (Ω); V_t : diode thermal voltage (V).

Our reference model is a 200W solar power module that is specified for installation. The characteristics are obtained from the manufacturer as shown in table 1.

Table 1:Electrical parameters for PV array

S/NO	PARAMETERS	VALUES
1	Maximum Power	200W
2	Maximum Power Voltage	24.6V
3	Maximum Power Current	8.13A
4	Open Circuit Voltage	30V
5	Short Circuit Current	8.56A
6	Reference Temperature	25°C
7	Module Efficiency	15.3%
8	Solar cell efficiency	17.2%
9	Maximum system voltage	1000V DC
10	Operating temperature	-40 ⁰ C – 85 ⁰ c (36 ⁰ C)
11	Total number of cells in parallel	72 (6x12)
12	Total number of cells in series1	

All electrical specifications are under test conditions of Irradiance of 1 kW/m^2 and cell temperature 25°C .

3.1 (a) Procedure for Modeling Solar PV Step by step

The modeling of the PV array has to do with the diode equivalent circuit fundamental equations; this will cover diode current source, series resistor, and parallel resistor. The entire modeling will be done with tags in Simulink environment. The simulation will be based on the equations stated above, that is (1) Module photocurrent (2) Module reverse saturation current, (3) Module Saturation current (4) The current output of PV model. (5) V_t thermal voltage, (6) shunt current I_{sh}

The equation given in [19] for $I_{sat} = I_{rs} \left[\frac{T}{T_r} \right]^3 \exp \left[\frac{q \times E_{g0}}{nk} \left(\frac{1}{T} - \frac{1}{T_r} \right) \right]$

A mathematical model of PV array including fundamental components of diode, current source, series resistor and parallel resistor is considered with Tags and modeled in Simulink environment.

(<http://mathwork.com>). The simulation of solar module is from the equations given in the previous section and will be followed sequentially.

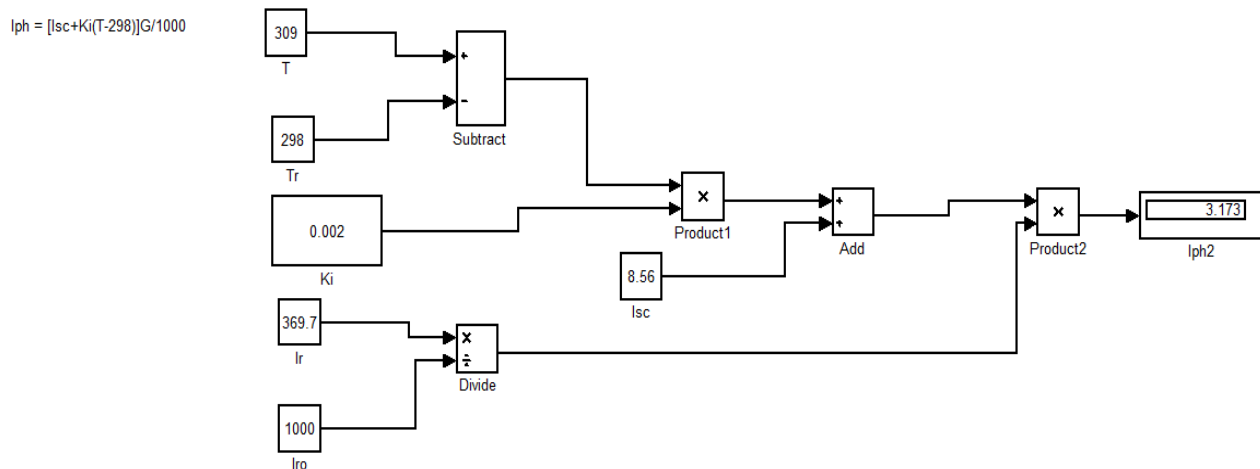
Step 1: Provision of input parameters

Input parameters for modeling are required,; These values are: T_r is reference temperature = 298K that is $(273+25)$; n is ideality factor = 1.2; k is Boltzmann constant = $1.3805 \times 10^{-23} \text{ J/K}$; q is electron charge = 1.6×10^{-19} ; I_{sc} is PV module short circuit current at 25°C and $1000 \text{ W/m}^2 = 8.56\text{A}$; V_{oc} is PV module open circuit voltage at 25°C and $1000 \text{ W/m}^2 = 30 \text{ V}$; E_{g0} is the band gap energy for silicon = 1.1 eV. R_s is series resistor, normally the value of this one is very small, = 0.0001Ω ; R_{sh} is shunt resistor, the value of this is so large, = 1000Ω .

3.2 Step 2

Module photon-current is given in Eq. (3.1) and modeled as Fig.3.8 ($I_{r0} = 1000 \text{ W/m}^2$).

$$I_{ph} = [I_{sc} + K_i(T - 298)] \times I_r / 1000 \quad (7)$$



CURRENT PRODUCED BY PV PANEL

Fig. 2: Modeled circuit of equation 1 PV photo current.

3.3 Step3: Module reverse saturation current from equation 2 $I_{rs} = I_{sc}/[\exp(qV_{oc}/NSknT) - 1]$
Module reverse saturation current is given in Eq. (2) and modeled as Fig 9.

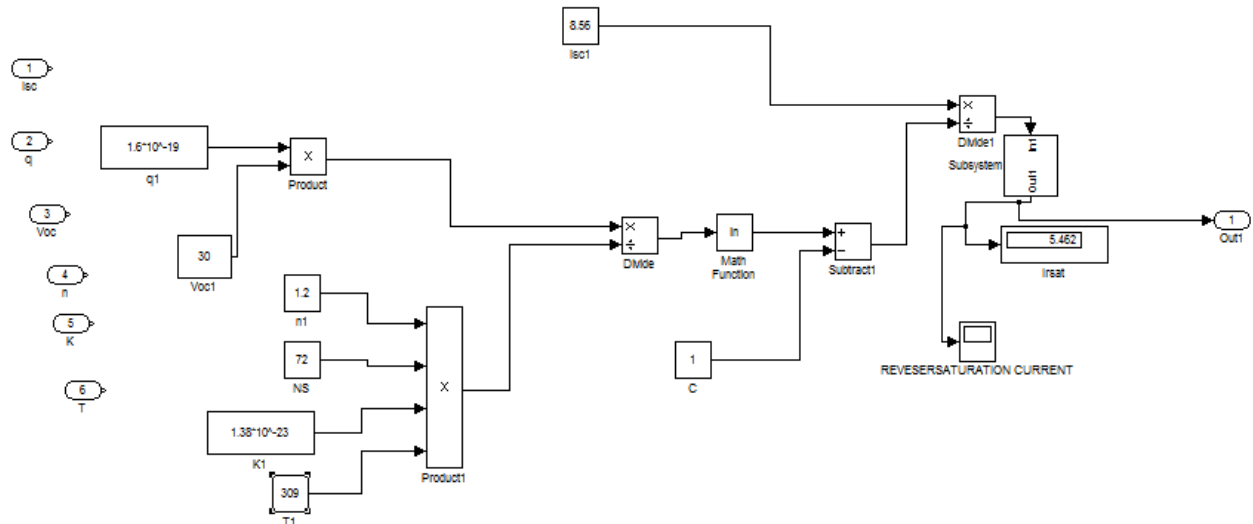


Fig.3 Modeled circuit for equation 2 reverse saturation current $I_{rsat} = I_{sc}/[\exp(qV_{oc}/NSknT) - 1]$

3.4 step 4 to calculate the module saturation current I_{sat} , as given in equation3

$$I_{sat} = I_{rs} \left[\frac{T}{T_r} \right]^3 \exp \left[\frac{q \times E_{g0}}{nk} \left(\frac{1}{T} - \frac{1}{T_r} \right) \right] \text{ and modeled as figure 4}$$

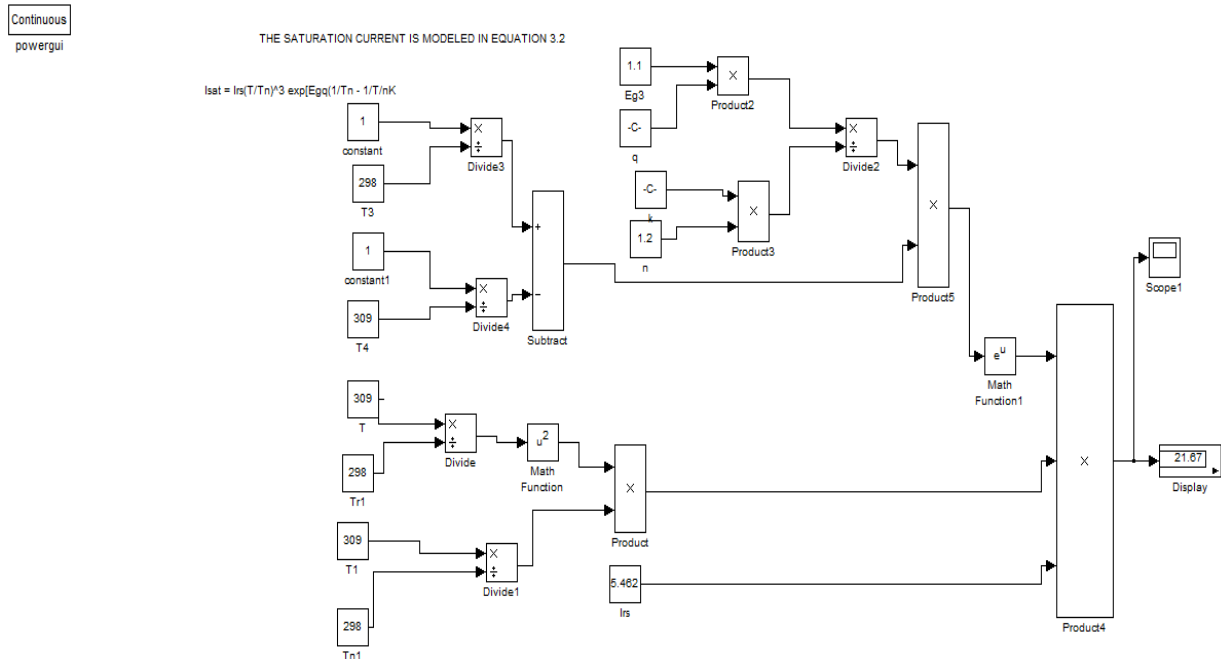


Fig.4: Modeled circuit for equation 3

3.5 Step 5

A modeled circuit for equation 3.6 is shown in figure 3.11, where the inputs are expressed in order to calculate the shunt current given as $I_{sh} = \frac{V \times N_p / N_s + I \times R_s}{R_{sh}}$

In this equation, N_p is the number of PV modules connected in parallel; R_s : series resistance in ohms; R_{sh} is the shunt resistance while V_t is the diode thermal voltage (v_t). The 200W solar panel is chosen as the reference module for simulation and the detailed parameters of module expressed as in table 3.

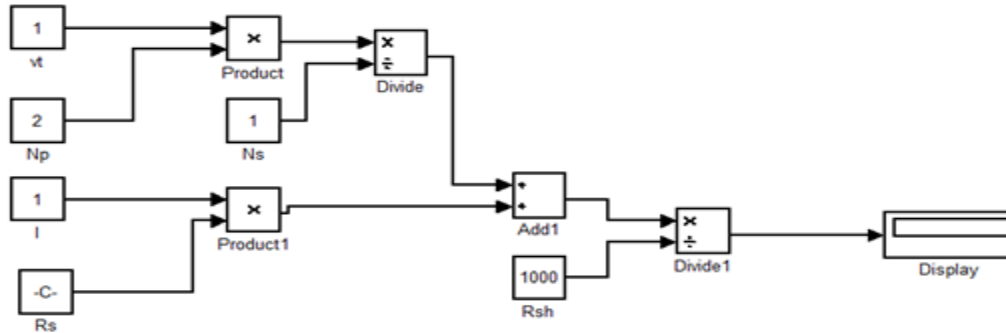


Fig.5: Modeled Circuit for shunt current of Equation 3.6

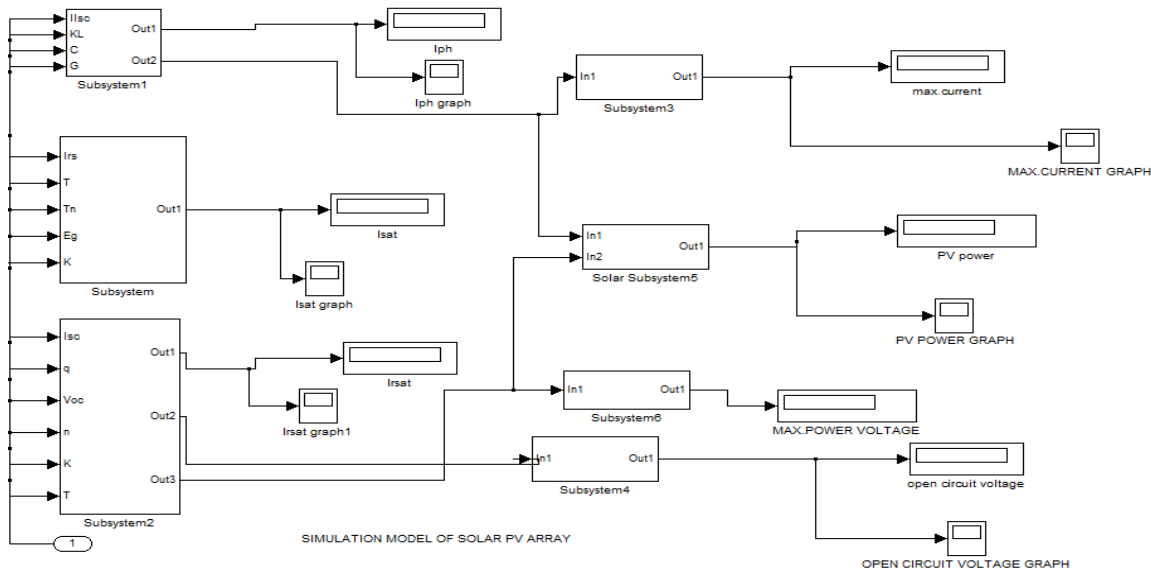


Fig.6: Interconnection of all subsystems of PV Module.

(b) Modeling of Wind Turbine

Wind energy falls under the class of a clean, friendly and endless source of energy. Therefore, a wind energy system is one of the preferred sources of alternative energy for the future demand. A wind turbine changes the, kinetic energy of wind into mechanical energy. The amount of this converted mechanical energy depends on the air density and the wind velocity. The power developed by the wind comes from the turbine and is expressed as

$$\frac{1}{2}C_p(\lambda, \beta)\rho A W^3 \quad (8)$$

Where

P_m power captured by wind turbine

ρ =Air density, β =Pitch angle (in degrees), r = Blade radius (in meters)

W = Wind Velocity (in m/s), the term λ is the tip-speed ratio, given by the equation

$$\lambda = \omega r / W \quad (9)$$

Where ω = rotor speed of rotation in (rad/sec)

C_p can be expressed as the function of the tip speed ratio (λ)[20](Ochieng, 2014)

$$C_p = \frac{1}{2} \left[\frac{116}{\lambda^1} - 0.4 \beta - 5 \right] \exp^{-165/\lambda} \quad (10)$$

$$\lambda_1 = \left(\frac{1}{\frac{1}{\lambda + 0.089} - \frac{0.035}{\beta^3 + 1}} \right)$$

(Ochieng, 2014)

(11)

λ = Tip speed ratio

λ_1 = constant

Where C_p = performance coefficient of turbine

ρ = air density (kg/m³)

A = area of turbine blades (m²)

w = wind velocity (m/sec)

λ = tip speed ratio of the rotor blade tip speed to wind speed

β = blade pitch angle (deg)

The coefficient C_p is the fraction of kinetic energy which is converted by wind turbine into mechanical energy. It is

related to the tip speed ratio (λ). Wind turbine output torque (T_m) can be calculated using equation [21](Anjali Rana, 2015):

$$T_m = \frac{1}{2} \rho A C_p \frac{W}{\lambda} \quad (12)$$

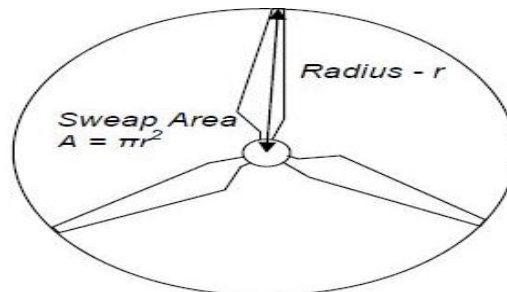


Fig. 7: Wind Turbine Blade

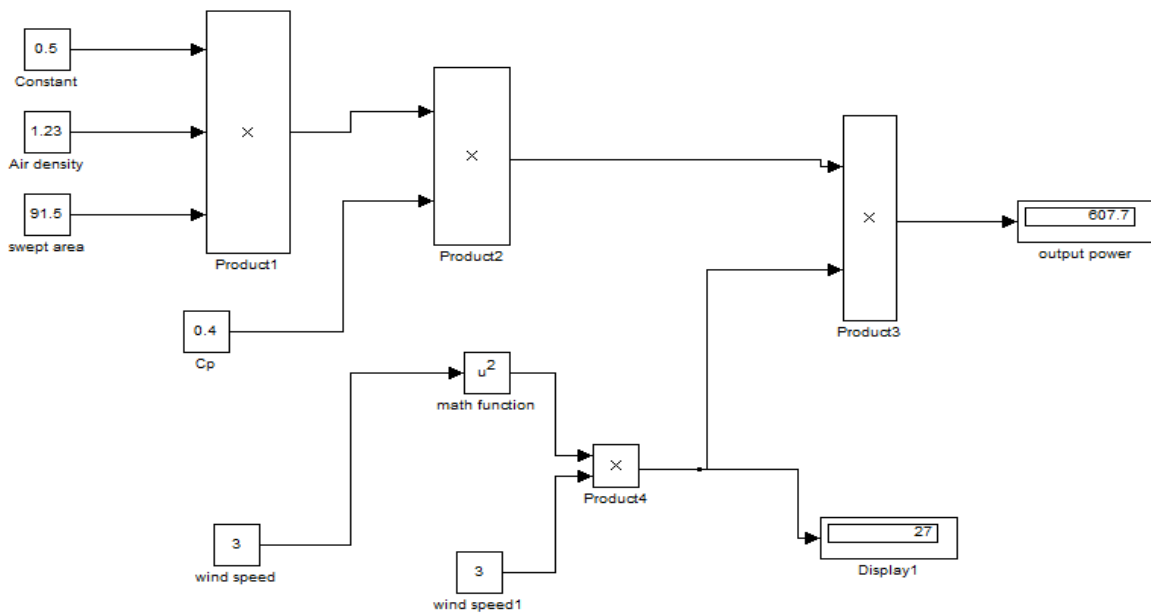
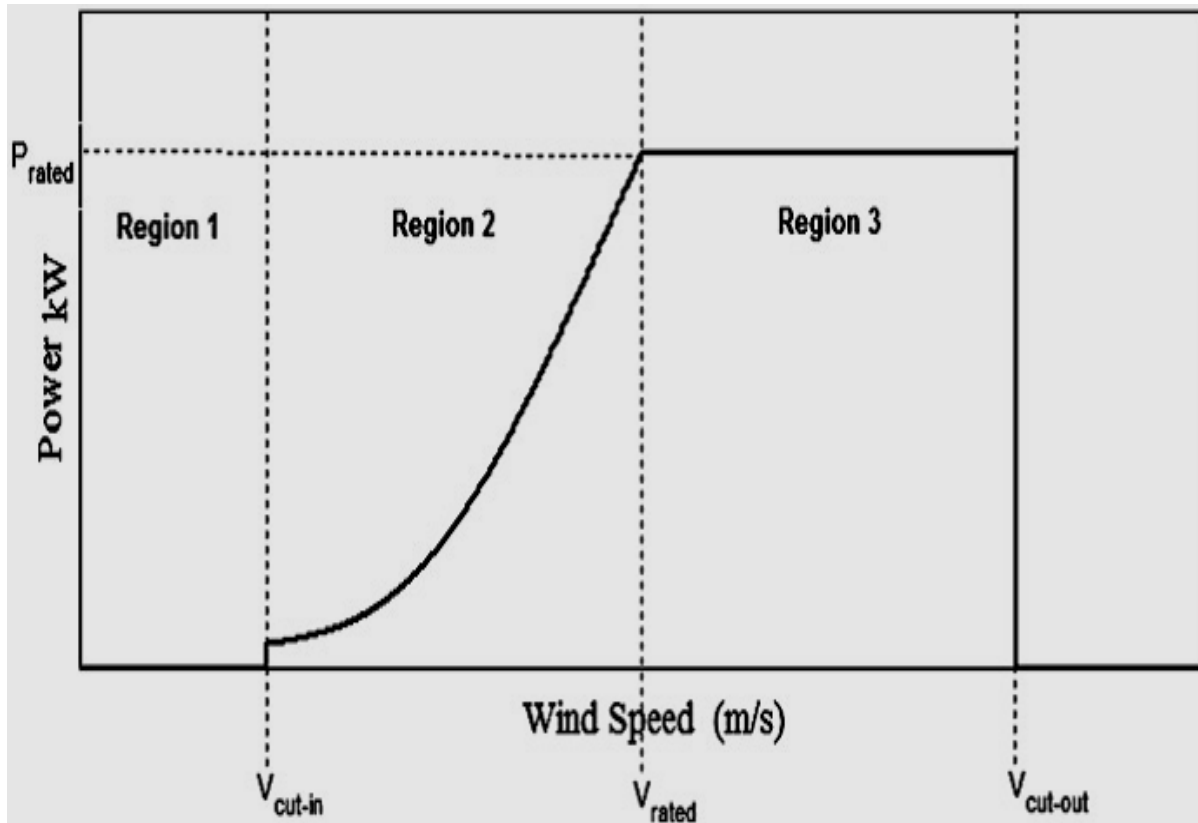
Fig. 8: Wind Turbine Model in Simulink equation $8.(1/2C_p(\lambda,\beta)\rho A W^3)$ 

Fig. 9: Ideal power curve of wind turbine courtesy of (Anjali Rana,2015)

This wind turbine is connected to a three phase synchronous generator which converts this mechanical power into electrical power. A single turbine is used in this work.

(c) Modeling of Hybrid PV/Wind System

A collection of Wind and PV energy system into a hybrid generation system can increase their efficiency by boosting their overall energy output, by reducing energy storage requirement. This makes system less costly and more reliable as compared to individual energy system.

A hybrid system of wind and PV connected together is simulated. It consists of a converter with PWM generator and voltage source converter which convert DC to AC of grid frequency. A Simulink model of hybrid system is shown in fig.10

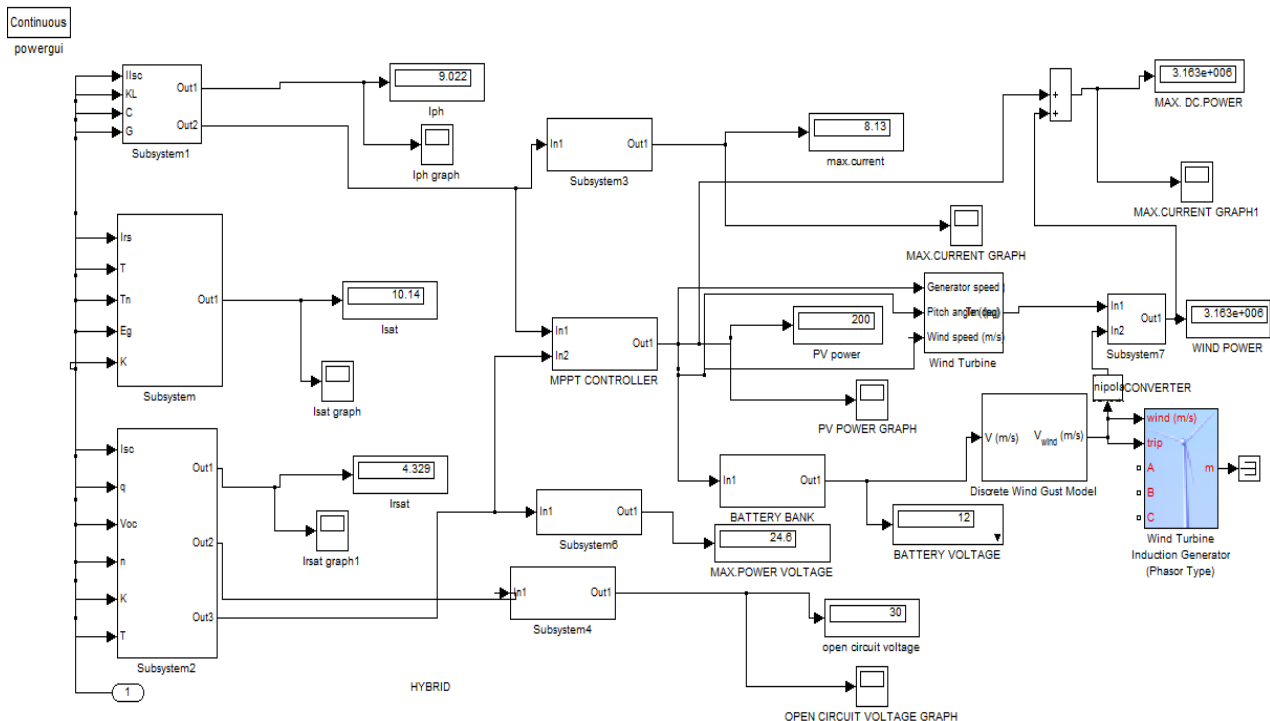


Fig. 10: Complete Simulink model of HRES wind/PV/Battery hybrid system

1. PV model in SIMULINK was simulated.
2. Wind Turbine performance was simulated and observed.
3. Battery Bank was modeled and simulated for charging and discharging capability.
4. The Hybrid Renewable Energy System (HRES) was used to power or supply electric energy to the residential Area. Simulation was done using an inductive motor that consumed the same load current as the residential load equivalent in rural area.

The graphs of figures 11 and 12 showed the output curves of the generated parameters

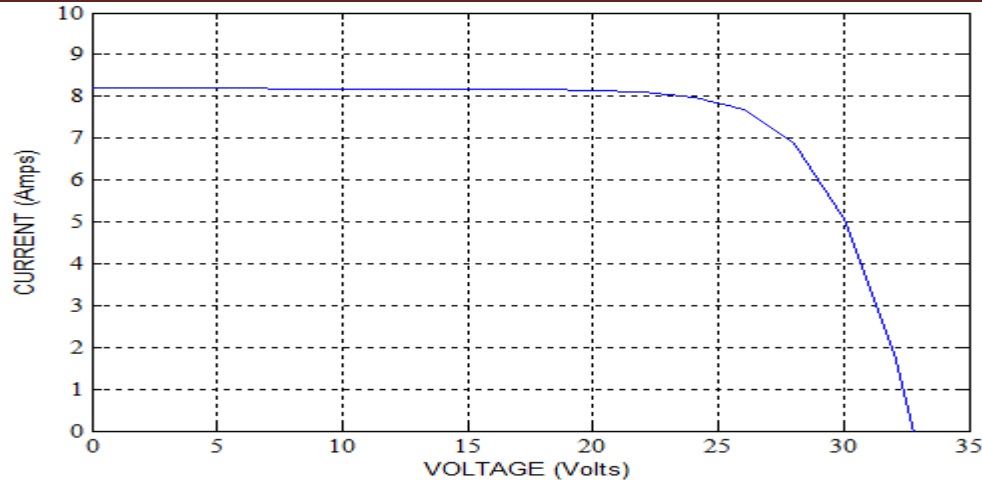


Fig.11: current –voltage curve of Photovoltaic Module

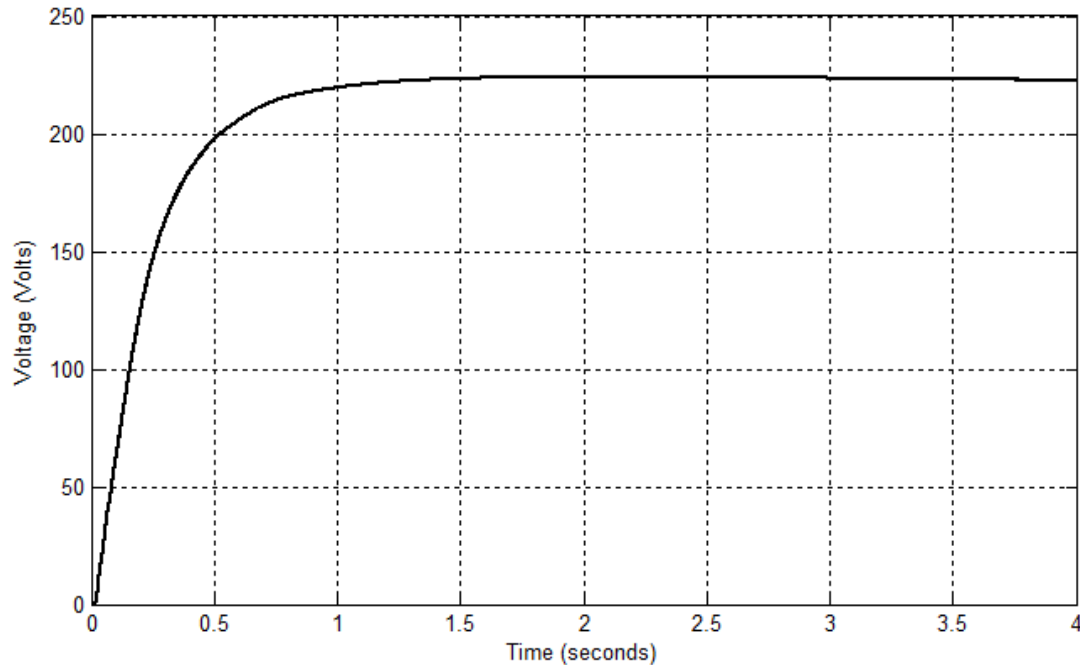


Fig. 12:Output voltage of a wind turbine

4.0 RESULTS AND DISCUSSION

The mathematical modeling of the PV was done step by step from fig.2 to fig.8, Wind Turbine performance was simulated and observed, the output voltage of the turbine was 240V, matched the calculated value.

A step-by-step procedure for simulating a PV array with Tag tools, using friendly icons and dialogues in Matlab/Simulink block libraries is shown in fig 5 and 6 respectively, where the simplified procedure was explained using SIMULINK.

5.0 CONCLUSION

A step by step method for simulating PV array and wind turbine with tag tools and user friendly icons and dialogs in Matlab/Simulink block libraries is illustrated. This modeling approach serves as an aid

to help people to have a deeper understanding of I-V and P-V operating curves of PV module. This paper is a step to study a hybrid system where a PV power generation connecting to other renewable Energy production sources like wind or biomass energy system are applied.

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